

TS-6623-R06 Series
Current Output Dual Inclinometer

Technical Manual

V1.0

Current Output Dual Axis Inclinometer

TS-6623-R06

FEATURES

- Dual Axis Inclination Measurement
- Resolution: 0.001°
- Power Supply: 12-36V
- Size: 3.54 × 1.59 × 1.02 (inch)
  90 × 40.5 × 26 (mm)
- Highest Accuracy: 0.01°
- Measurement Range: ±90°
- Output: 4-20mA/0-20mA/0-24mA Optional
- IP67 Protection Level

APPLICATIONS

- Industrial Automatic Leveling
- Medical Instruments
- Photovoltaic Automatic Tracking
- Tower Tilt Monitoring
- Structural deformation monitoring
- Surveying and Mapping Instruments
- Equipment automation
- Lifting Equipment Inclination Control

DESCRIPTION

The TS-6623-R06 is a cost-effective dual-axis inclinometer developed and produced by AIT Sensing, which adopts MEMS technology and current output. It has a measurement range of ±90°, the highest accuracy of 0.01°, and an operating temperature of -40°C to +85°C. The product uses a high-precision MEMS accelerometer and a high-resolution differential digital-to-analog converter, with built-in automatic compensation and filtering algorithms, which eliminates errors caused by environmental changes to the greatest extent. Convert the change of the static gravity field into the change of the inclination angle, and directly output the horizontal inclination value through the digital method. This product has high long- term stability, low temperature drift, simple use, and strong ability to resist external interference. It is used for surveying and mapping, industrial automation and other industries.

SPECIFICATIONS

Table 1.

Parameter	Test Conditions	Min.	Typ.	Max.	Unit/Note
Power Supply Voltage		12		36	V
Operating Current	No load	20	50	60	mA
Output Load	Max			500	Ω
Operating Temperature Range		−40	25	85	°C
Storage Temperature Range		−55	25	100	°C
Measurement Range			±90		°
Measurement Axis		X-Y			

Parameter	Test Conditions	Min.	Typ.	Max.	Unit/Note
Accuracy	Room temperature		0.01		°
Resolution	Completely still		0.001		°
Zero Bias	−40 ~85℃	−0.01		+0.01	°/℃
Cross Axis Error			0.01		°
Current Output at Zero	Output: 0 ~ 20 mA		10		mA
	Output: 4 ~ 20 and 0 ~ 24mA		12		
Full-Scale Output Current Range	0-20 or 0-24 optional	4		20	mA
Mean Time Between Failures MTBF		90000			h
Electromagnetic Compatibility		According to GBT17626			
Insulation Resistance		100			MΩ
Impact Resistance		2000g, 0.5ms, 3 times/axis			

*Resolution: The smallest change value of the measured value that the sensor can detect and distinguish within the measurement range.

*Accuracy: The root mean square error of the actual angle and the sensor measuring angle for multiple (≥16 times) measurements.

ELECTRICAL INTERFACE

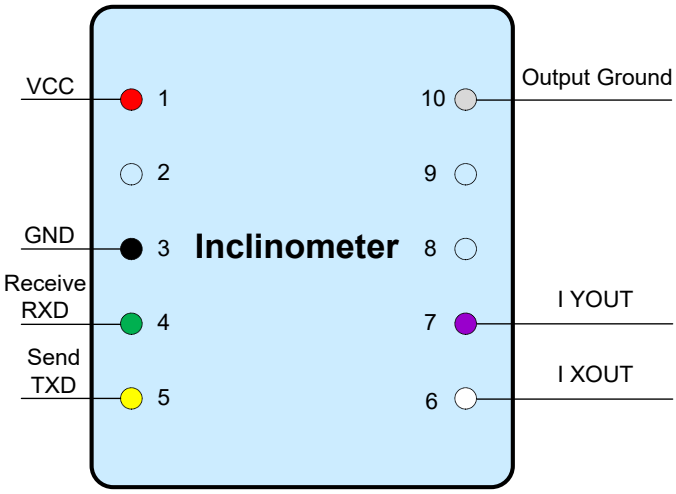


Figure 1. Pin Names

Table 2. Pin Number, Colors and Functions

No.	Color		Functions
1		Red	VCC: DC 12V ~ 36V
2		Blue	NC
3		Black	Ground
4		Green	Receive RXD
5		Yellow	Send TXD
6		White	I XOUT
7		Purple	I YOUT
10		Grey	Output Ground

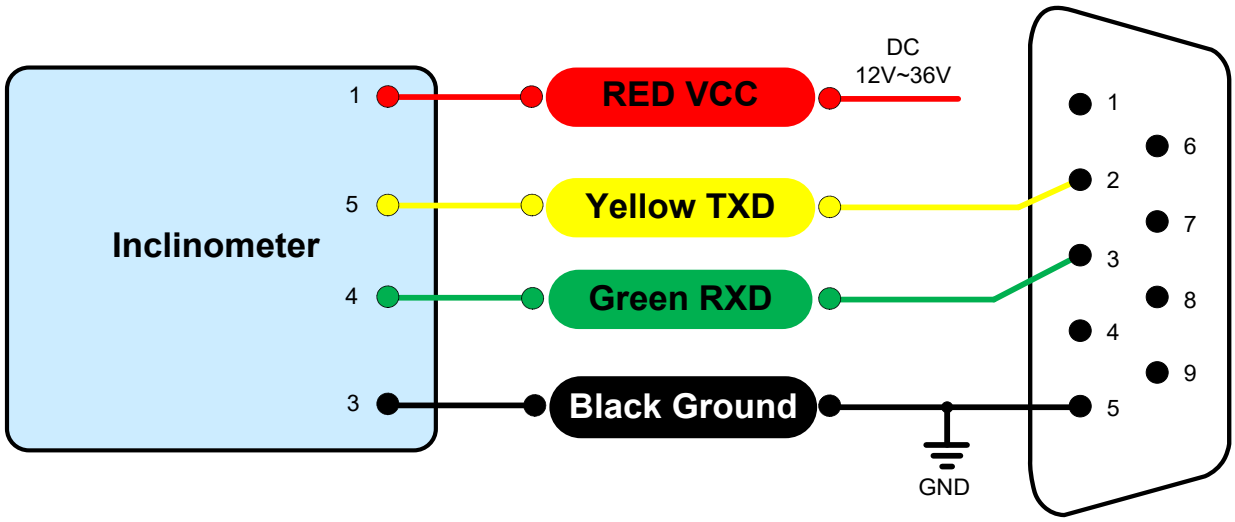


Figure 2. RS 232 Wiring Diagram

DEBUGGING SOFTWARE

You can download the serial debugging assistant directly on the official website (technical service -> download area), or you can use the more convenient and intuitive host computer software.

TS-6623-R06 supporting serial port debugging software can connect the inclination sensor on the computer to display the angle. The software debugging interface is shown in the figure below. Using the tilt angle to debug the host computer, you can conveniently display the current X direction and Y direction tilt angle, and you can also modify and set other parameters.

Steps:

(1). Correctly connect the serial port hardware of the inclinometer and connect the power supply.

(2). Select the computer serial port and baud rate and click to connect to the serial port.

(3). Click Start, the current tilt angle of the inclinometer in the X and Y directions will be displayed on the screen.

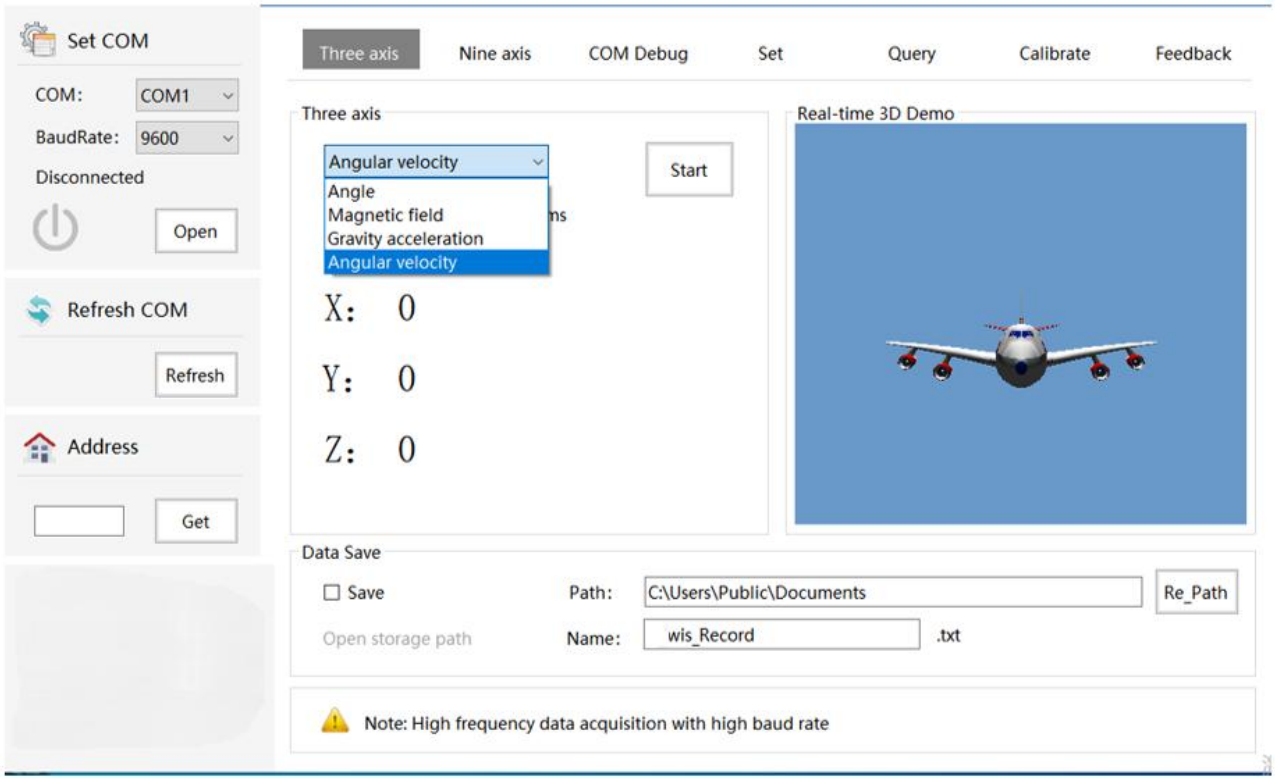
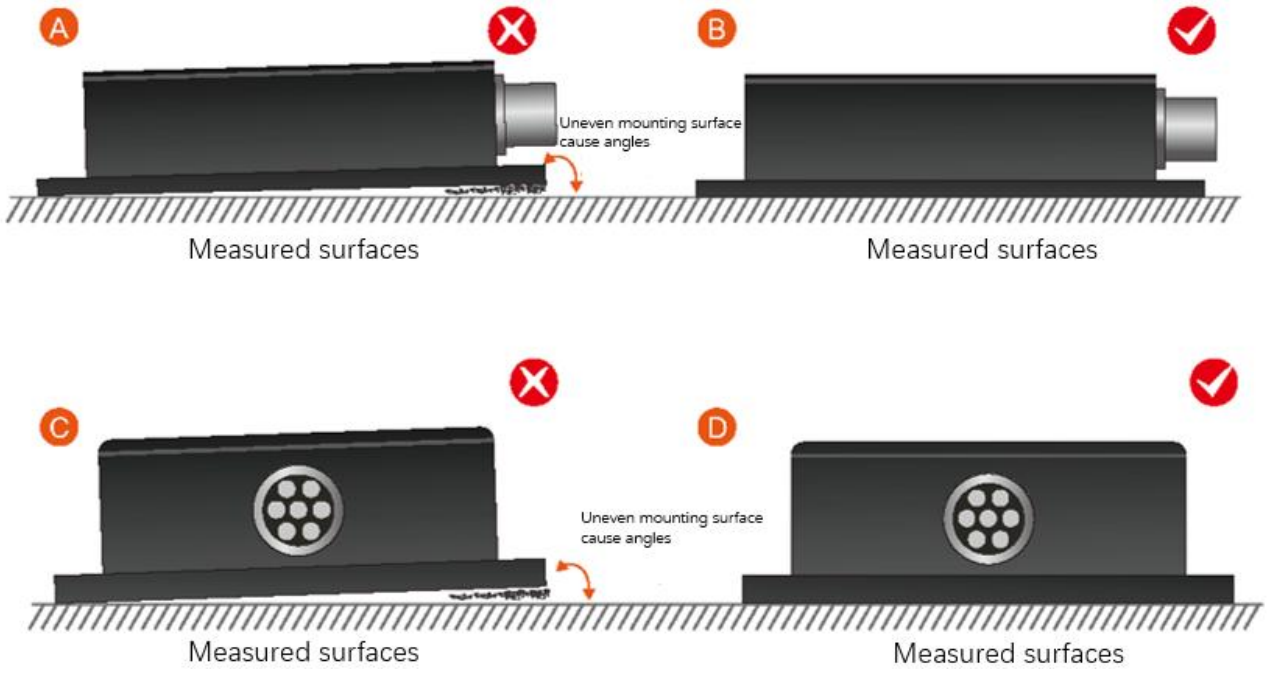


Figure 3. Software Debugging Interface

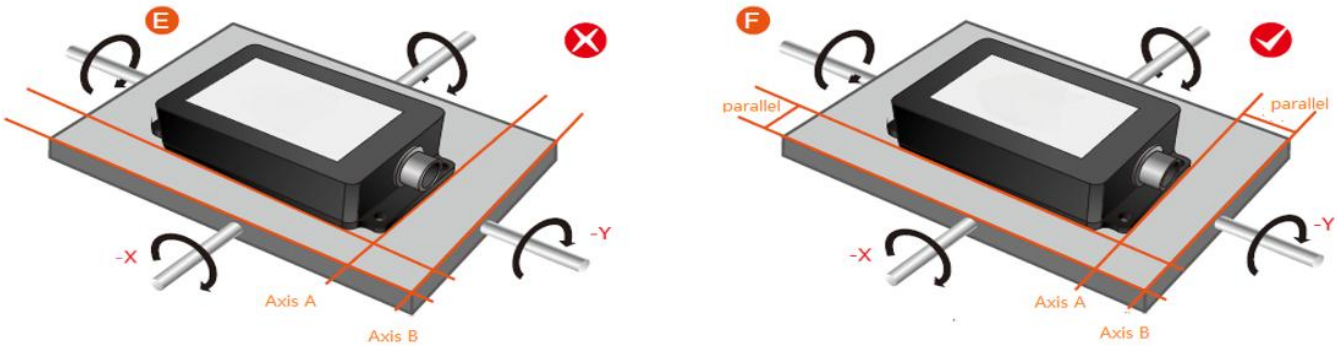
INSTALLATION

The correct installation method can avoid measurement errors. When installing the sensor, please do the following:

First of all, make sure that the sensor mounting surface is completely close to the measured surface, and the measured surface should be as level as possible. There should be no included angles as shown in Figure A and Figure C. The correct installation method is shown in Figure B and Figure D.



Secondly, the bottom line of the sensor and the axis of the measured object cannot have an angle as shown in Figure E, and the bottom line of the sensor should be kept parallel or orthogonal to the axis of rotation of the measured object during installation. This product can be installed horizontally or vertically (vertical installation needs to be customized), and the correct installation method is shown in Figure F.



Finally, the mounting surface of the sensor and the surface to be measured must be tightly fixed, smooth in contact, and stable in rotation, and measurement errors due to acceleration and vibration must be avoided.

DIMENSIONS

Outline Dimensions

Top View	Side View
Unit	mm (inch)

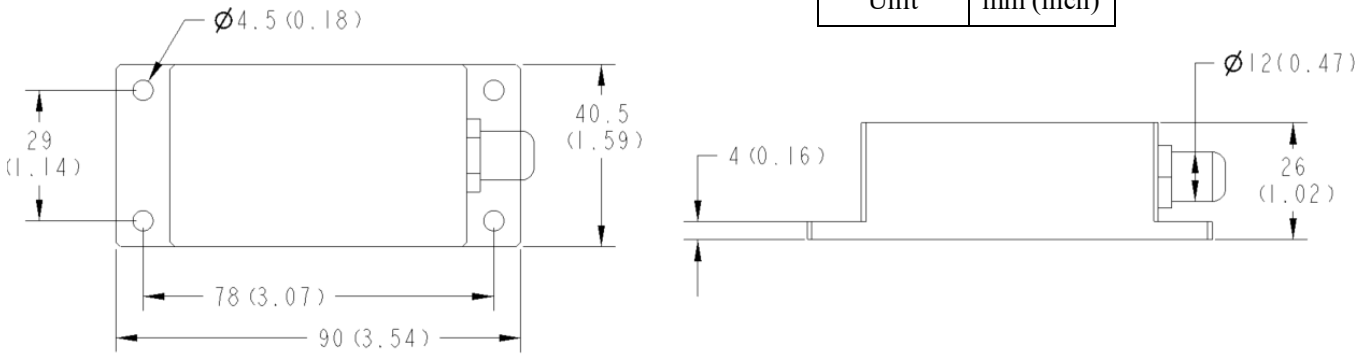
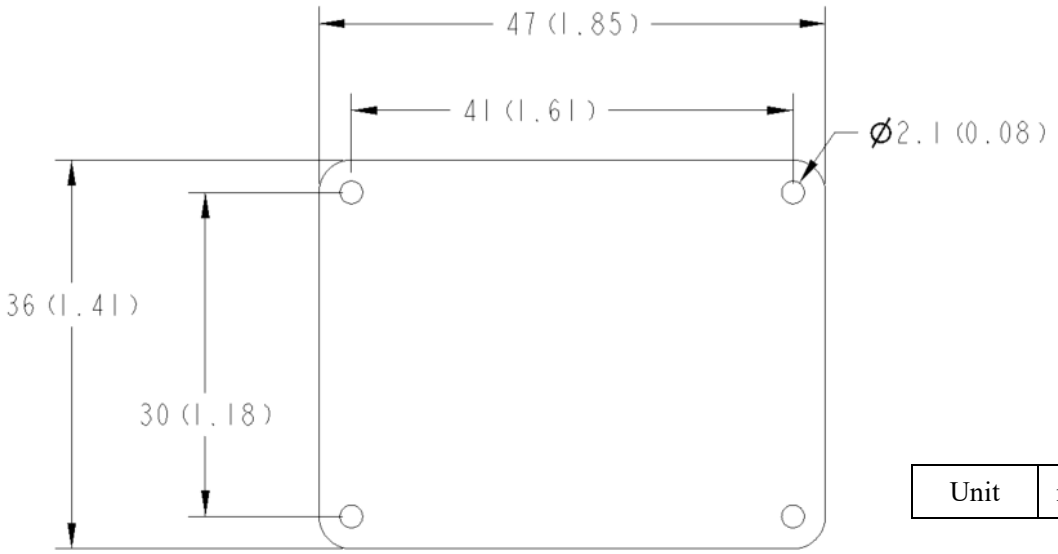


Figure 4. Outline Dimensions

PCB Dimensions

The length and width may have an error of ±1mm, please refer to the actual product.



Unit	mm (inch)

Figure 5. PCB Dimensions



Figure 6. Top View of TS-6623-R06

Table 3. Mechanical Index

Connector	Metal joint（Cable 1.5m)
Protection Level	IP67
Shell Material	Magnesium aluminum alloy oxidation
Installation	Four M4 screws