

FEATURES

High Efficiency: $\geq 90\%$
Maximum Output Current: 6A
Current Output Noise: $8.66\mu A_{P-P}@0.1Hz \sim 10Hz$
High Stability: $\pm 12mA@6A$ (0.2%) for entire temp. range
Loop Good Indication
Fully shielded
Compact Size
100 % lead (Pb)-free and RoHS compliant

APPLICATIONS

Driving laser diodes, DPSSL, EDFA, fiber laser, direct diode laser, etc., with low noise and high efficiency.

DESCRIPTION

This laser driver, ATLS6A201D, is an electronic module designed for driving diode lasers by up to 6A constant current with high efficiency, low noise, high reliability, zero EMI, and small package. There are two types: ATLS6A201D and ATLS6A201D-PD, and the latter has a pull-down resistor to the ground. Figure 1.1 shows physical photo of the ATLS6A201D and Figure 1.2 shows the photo of ATLS6A201D-PD.

It provides these functions: laser current control, laser current monitoring, over temperature protection, loop good indication, laser diode status indication, soft start, and shut down.

It comes with a high stability low noise 2.5V voltage reference output which can be used for setting the output current and, at the same time, for the ADCs (Analog to Digital Converters) and/or DACs (Digital to Analog Converters) as the reference voltage.

Table 1. Pin Function Descriptions

| Pin # | Name | Type | Description |
|-------|-------|----------------|---|
| 1 | SDN | Digital Input | ATLS6A201D: Shut down control. Negative logic, at the internal chip control input: $>1.4V$ = enable, $<0.95V$ = shut down. ATLS6A201D-PD: Shut down control. Positive logic, at the internal chip control input: $<0.95V$ = enable, $>1.4V$ = shut down. There is a pull-down resistor of 55k to the ground. |
| 2 | LDGD | Digital Output | Laser diode good indication. When this pin is high, $>2V$, the control loop is working properly. When this pin is low, $<0.3V$, the laser diode is bad, or there is a short or open circuit at the laser diode. |
| 3, 7 | GND | Signal Ground | Signal ground pin. Connect ADC and DAC grounds to here. When using a POT (potentiometer) to set the output current, connect the ground terminal of the POT to here. |
| 4 | 2.5VR | Analog Output | Reference voltage. It can source 3mA max, with $5\mu V_{P-P}$ noise between 0.1 to 10Hz and 25ppm/ $^{\circ}C$ stability max. |
| 5 | LIS | Analog Input | Laser current setting voltage. There is an input resistor of 10M tied to GND. Setting it from 0V to 2.5V will set the laser current from 0A to 6A linearly. |
| 6 | LIO | Analog Output | Laser current output indication. 0V to 2.5V indicates the laser current being from 0A to 6A linearly. |

Warning: This module can only be soldered manually on the board by a solder iron at $< 310^{\circ}C$ ($590^{\circ}F$), it cannot go through a reflow oven process.



Figure 1. Physical Photo of ATLS6A201D

The ATLS6A201D is packaged in a 6 sided metal enclosure, which blocks EMIs (Electro-Magnetic Interferences) to prevent the driver and other electronics from interfering leach other.

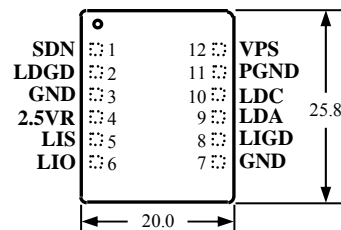


Figure 2. Pin Names and Locations

Figure 2 is the actual sized top view of the ATLS6A201D, which also shows the pin names and locations. Its thickness is 5mm. The pin functions are described in Table 1 below.



| | | | |
|----|------|---------------|---|
| 8 | LIGD | Analog Output | Laser current good indication. When this pin is stabilized and the value is between 1V and 2.4V, the output voltage to the laser at pin 9, LDA, will be 4.5V to 0V linearly, the laser current is stabilized, and the control loop is stable. |
| 9 | LDA | Analog Output | Laser diode anode. Connect it to the anode of the laser diode. |
| 10 | LDC | Analog Output | Laser diode cathode. Connect it to the cathode of the laser diode. |
| 11 | PGND | Power Ground | Power ground pin. Connect this pin directly to power supply return path line. |
| 12 | VPS | Power Input | Power supply voltage. The driver works from $V_{VPS} = 3.0V$ to $5.5V$. |

SPECIFICATIONS

Table 2. Characteristics ($T_{\text{ambient}} = 25^{\circ}\text{C}$)

| Parameter | Test Condition | Value | Unit |
|---|---|-------------------------------|---|
| Laser driver efficiency | $I_{\text{OUT}} = 3A$, $V_{\text{OUT}} = 2.5V$, & $V_{\text{VPS}} = 5V$ | ≥ 90 | % |
| | $I_{\text{OUT}} = 5A$, $V_{\text{OUT}} = 1.4V$, & $V_{\text{VPS}} = 5V$ | 77.2 | |
| Maximum output current | $V_{\text{LDA}} \leq V_{\text{LDAMAX}}$ | 6 | A |
| Output current noise ($V_{\text{IN}} = 5V$; $V_{\text{OUT}} = 2.5V$; $I_{\text{OUT}} = 500\text{mA}$) | $V_{\text{IN}} = 5V$; $V_{\text{OUT}} = 2.5V$; $I_{\text{OUT}} = 500\text{mA}$ | 8.66 | $\mu\text{A}_{\text{P-P}}$ @0.1Hz- 10Hz |
| Stability @ 1A | The range of T_A is $20^{\circ}\text{C} \sim 80^{\circ}\text{C}$ | ± 0.2 | % |
| Laser current control signal range at LIS | $V_{\text{VPS}} = 3.1V \sim 6V$ | $0 \sim V_{\text{VPS}} - 0.2$ | V |
| LIS control accuracy | Relative accuracy = (accuracy current – set point current) / set point temp. | ± 0.2 | % |
| Laser current indication signal range at LIO | $V_{\text{VPS}} = 3.1V \sim 6V$ | $0 \sim 2.5$ | V |
| LIO indication accuracy | $V_{\text{VPS}} = 3.1V \sim 6V$ | ± 0.2 | % |
| Reference voltage | $V_{\text{VPS}} = 3.1V \sim 6V$ | 2.5 | V |
| Reference Voltage temperature co efficiency | $V_{\text{VPS}} = 3.1V \sim 6V$ | | |
| Output voltage range at LDA | $V_{\text{VPS}} = 3.1V \sim 6V$ | Depending on V_{VPS} | V |
| PWM frequency | | 500 | kHz |
| Power supply voltage range | | $3.1 \sim 6$ | V |
| Maximum power supply voltage | – | 6 | V |
| Start-up time | | 4 | ms |
| Typical pull-down current at LDGD | | 6 | mA |
| Operating case temperature | $I = 1A$, $V_{\text{IN}} = 3.3V$ or $5V$, $V_{\text{OUT}} = 2.5V$ | $-40 \sim 85$ | $^{\circ}\text{C}$ |
| Rise times of small signal | $I_{\text{OUT}} = 1A$, $V_{\text{OUT}} = 2.5V$, & $V_{\text{VPS}} = 5V$ | 70 | μS |
| Fall times of small signal | $I_{\text{OUT}} = 1A$, $V_{\text{OUT}} = 2.5V$, & $V_{\text{VPS}} = 5V$ | 70 | μS |
| Rise times of large signal | | 352 | μS |
| Fall times of large signal | | 184 | μS |

OPERATION PRINCIPLE

The block diagram of the driver is shown in Figure 3. The shutdown control circuit accepts signals from 3 sources: external shut down, over current and over temperature signals. When any of these signals is activated, the driver is shut down. Only when none all these 3 signals is activated, a soft start circuit starts enabling the driver stage.

The soft start circuit increases the output current slowly at the start up time and shuts down the current quickly. Thermal shutdown circuit turns the driver off if the junction temperature exceeds 150°C . The driver is released from

shutdown automatically when the junction temperature decreases to 10°C below the thermal shutdown trip point, and starts up under control of the soft start circuit. The over current protection circuit turns the driver off if the output current exceeds $10A @ V_{\text{VPS}} = 3V$ or $12A @ V_{\text{VPS}} = 6V$.

The high stability low noise 2.5V voltage reference is provided for setting the output current by setting the LIS' voltage, and can also be used for the ADCs and/or DACs.

The laser diode status indication circuit monitors laser diode status. When LDGD pin is high, $>2V$, the control loop is

working properly; when this pin goes low, <0.3V, the laser diode is bad, or there is a short or open circuit at the laser diode.

The laser current control indication circuit shows the driving status for the output current. When this voltage is between 0.2V to 1.8V, the output voltage on the laser diode is between 4.8V to 0V.

The current measurement circuit monitors the output current and shuts down the driver upon detecting the output current exceeds the pre-set value. It also provides a signal, LIO, indicating the actual laser diode current. The relationship is:

$$\text{Laser current} = 2.4 \times V_{\text{LIO}} \text{ (A)}.$$

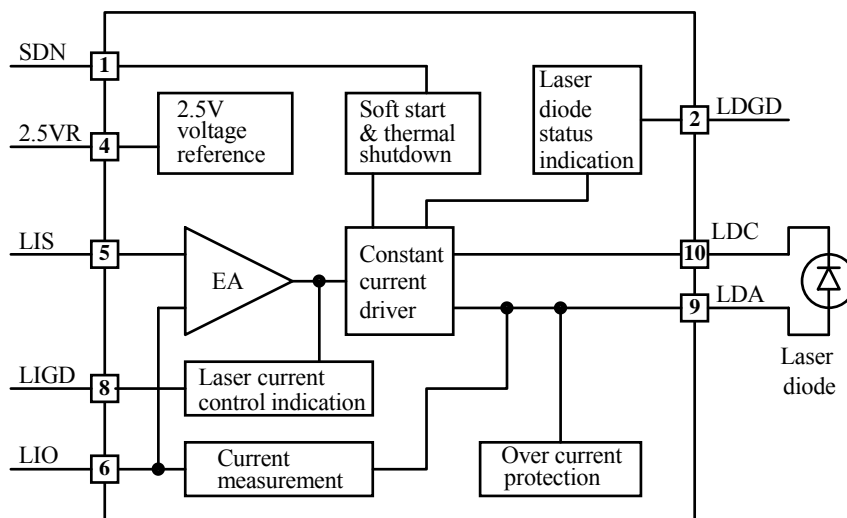


Figure 3. Block Diagram

APPLICATION INFORMATION

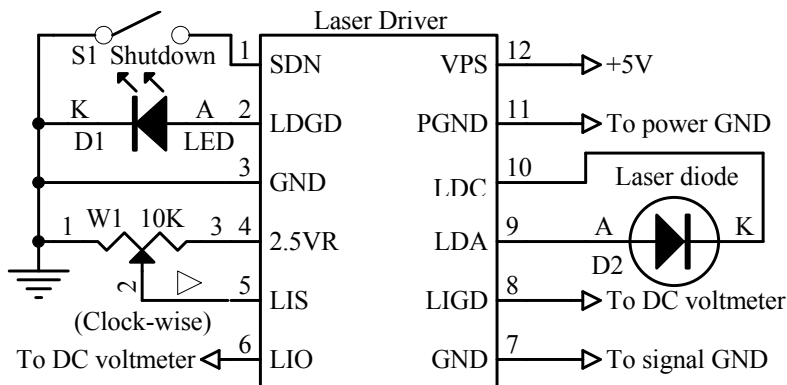


Figure 4.1. A Typical Stand-alone Application Schematic for ATLS6A201D

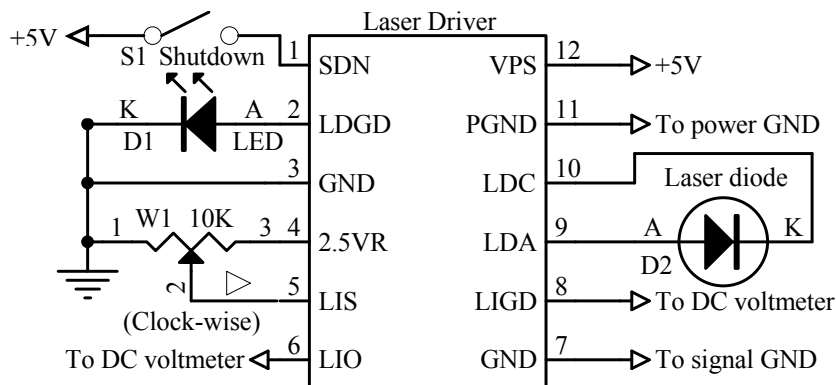


Figure 4.2. A Typical Stand-alone Application Schematic for ATLS6A201D-PD

Figure 4.1 and 4.2 show the typical stand-alone application circuits for ATLS6A201D and ATLS6A201D-PD respectively.

In Figure 4.1, the switch S1 is an external shut down switch, which turns the driver off and on by tying SDN pin to the ground or releasing it respectively. In Figure 4.2, the switch S1 is an external shut down switch, which turns the driver off and on by tying SDN pin to VPS or releasing it respectively. The starting up time delay is about 4ms and the shut down time is about 20μs.

The switch S1 can also be an electronic switch, such as an I/O pin of a micro-driver, with an either open drain or push/pull output. See Figure 5. For ATLS6A201D, the internal equivalent circuit is a resistor of 10M pulling up this pin to VPS rail. And for ATLS6A201D-PD, the internal equivalent circuit is a resistor of 55k pulling down this pin to GND. When this pin voltage is >1.4V, the driver is enabled; <0.95V, the driver is shut down. Normal threshold voltage = 1.2V.

If not using a switch (S1) to control the laser, leave the SDN pin unconnected.

In Figure 4.1, the LED D1 is used to indicate laser diode status. When LDGD pin is high, >2V, the laser diode control loop is working properly. When LDGD pin is low, <0.3V, the laser diode is bad, or there is a short or open circuit at the laser diode. The LDGD pin can also be connected to a digital input pin of a micro-driver, when software/firmware

is utilized in the system. See Figure 5. The equivalent circuit of this pin is a 5k resistor pulling up it to the VPS rail and an open drain FET pulling it down to the ground. The pull-up current can be increased by connecting an external pull-up resistor between VPS and LDGD pins, which is equivalent to paralleling the external resistor with the internal 5k pull-up resistor. However, the total pull-up resistor should be $\geq 1.5k @ V_{VPS}=5V$ or $\geq 1k @ V_{VPS}=3.3V$, otherwise, the internal open drain FET cannot provide the resistors with enough pull-down current to achieve a low enough potential level for a logic low indication. To calculate the total pull-up resistor, use the equation below:

$$R_{TOTAL} = (R_{INTERNAL} \times R_{EXTERNAL}) / (R_{INTERNAL} + R_{EXTERNAL})$$

where:

R_{TOTAL} is the total pull-up resistor,

$R_{INTERNAL}$ is the internal pull-up resistor,

$R_{EXTERNAL}$ is the external pull-up resistor.

The laser diode D2 is connected between LDA and LDC. It is worth mentioning that the power supply return terminal should be connected to the pin 11 PGND and the cathode of the laser diode should be connected to the pin 10 LDC. These 2 pins, 10 and 11, should not be connected together externally and they are connected together internally already by the driver.

Figure 5 shows a typical micro-processor-based application circuit.

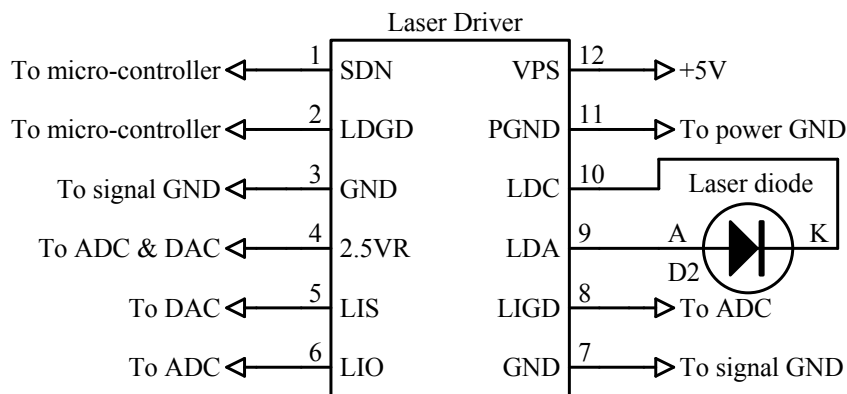


Figure 5. A Typical Micro-processor-based Application Schematic

Turning the Driver On and Off

The driver can be turned on and off by setting the SDN pin high and low respectively. It is recommended to turn the driver on by this sequence:

To turn on: turn on the power by providing the power supply voltage to the driver on VPS pin, turn on the driver by releasing the SDN pin.

To turn off: turn off the driver by lowering the voltage of SDN pin, turn off the power by stopping the voltage supply on the VPS pin.

When not controlling by the SDN pin: leave it unconnected and turn on and off the driver by the power supply.

Adjusting the Output Current

The output current is set by adjusting W1, which sets input voltages of LIS, pin 5. See Figure 4.1 The output current will be:

$$I_{OUT} (A) = 6.0 (A) \times V_{LIS} (V) / 2.5 (V).$$

LIS can be configured by using a DAC, to replace the W1 in Figure 4.1. Make sure that the DAC has output low noise, or,

if no modulation is needed, an RC low pass filtered by be inserted between the DAC and the LIS pin. See Figure 5.

The LIO can still be used to monitor the output current when the LIS is adjusted. 0V to 2.5V indicates the laser current of from 0A to 6A linearly.

Monitoring the Output Current

The output current of the driver can be monitored by measuring the voltage on the LIO pin. This feature is very useful for micro-driver based system where the ADC is available and monitoring the current in real time is required. This pin provides a very low noise voltage signal and is proportional to the output current:

$$V_{LIO} (V) = 2.5 (V) \times I_{OUT} (A) / 6.0 (A).$$

For example, when the output signal is 2.5V, the output current is 6A.

LIO can be used to drive an ADC directly, and also be measured by a multi-meter.

Figure 6 shows the relationship between Pin VPS and LDA.

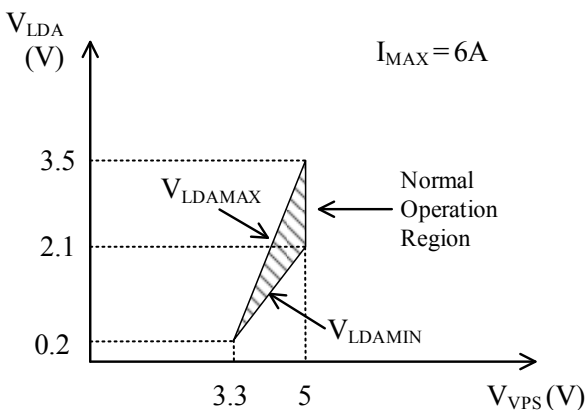


Figure 6. V_{VPS} vs. V_{LDA}

Driver Power Consumption

The power consumption of the driver can be calculated by:

$$P_{DRIVER} = I_{IN} \times V_{VPS} - I_{OUT} \times V_{LDA},$$

where P_{DRIVER} is the power consumed by the driver itself; I_{OUT} is the output current;

I_{IN} is the power supply's input current;

V_{VPS} is the power supply voltage;

V_{LDA} is the voltage across the laser diode;

$$\eta = (I_{OUT} \times V_{LDA}) / (I_{IN} \times V_{VPS}).$$

When the P_{DRIVER} exceeds 1W, a heat sink might be needed. The best way for arranging the heat sinking for the driver is as follows: transferring the heat by sandwiching a piece of thermal conductive pad between the top metal surface of the laser driver and the internal metal surface of the final product as shown in Figure 7.1 and 7.2 below. The recommended thickness of the thermal conductive pad in Figure 7.1 is 1~4mm, and in Figure 7.2 is 0.5mm. ATI also provides a series of thermal conductive pads, click [here](#) for more information.

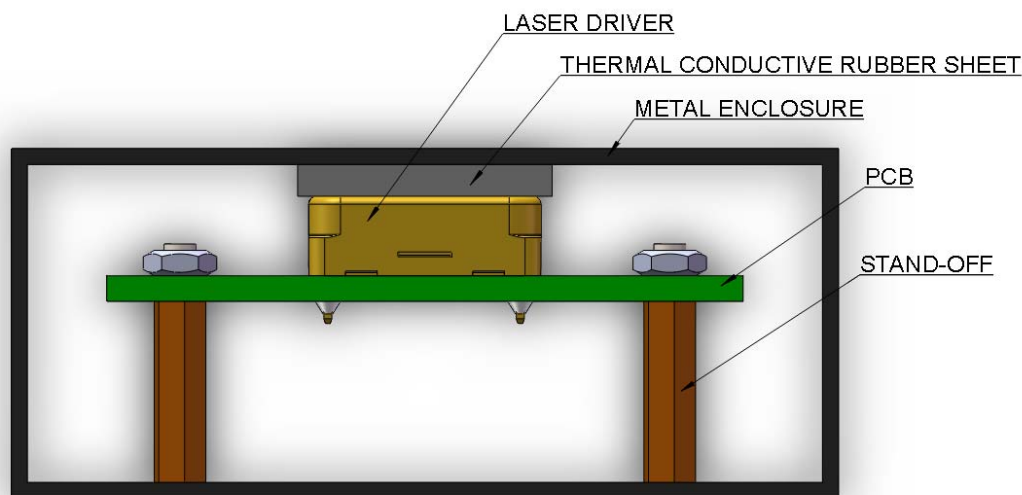


Figure 7.1 Transferring Heat with Metal Enclosure

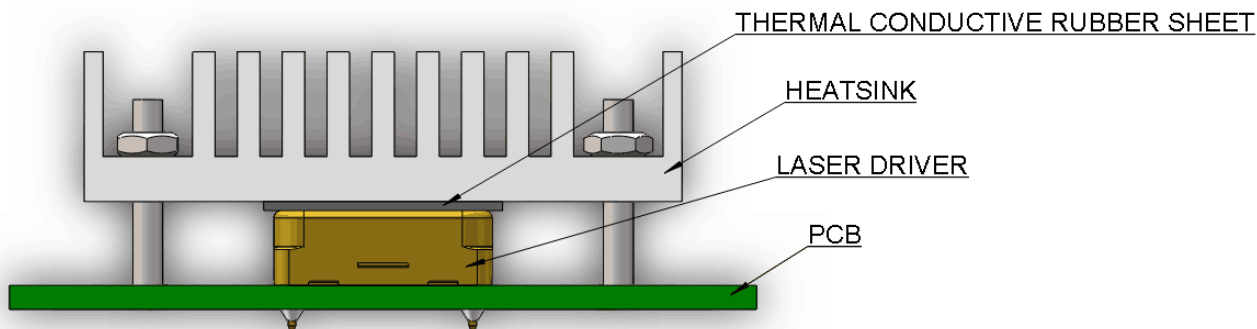


Figure 7.2 Transferring Heat with Heat Sink

To reduce the power consumed by the driver, we recommend using a power supply with its voltage barely higher than

$$1.2 \times V_{LD\text{MAX}}$$

where $V_{LD\text{MAX}}$ is the maximum possible laser diode voltage.

For example, for most diode lasers at 6A, the maximum forward voltage across the laser is about 2.7V, thus, use a 3.3V power supply is enough. Using a 3.3V power supply results in a much lower power consumption by the driver than using a 5V power supply.

First Time Power Up

Laser diode is a high value and vulnerable device. Faults in connections and damages done to the driver during soldering process may damage the laser diode permanently.

To protect the laser diode, it is highly recommend to use 3 to 4 regular diodes of >6A to form a “dummy laser” and insert it in the place of the real laser diode, when powering up the driver for the first time. Use an oscilloscope to monitor the LDA voltage at times of powering up and enabling the shutdown pin, and powering down the laser driver and turning off the shutdown pin, and make sure that there is not over-shoot in output voltage at the LDA pin. At the same time, use an ammeter in series with the dummy laser, to make sure that the output current is correct.

After thorough checking and making sure free of faults in

the system, disconnect the dummy laser diode and connect the real laser diode in place.

The driver output voltage range for the laser is between 0 to $0.85 \times V_{VPS}$.

The rise and fall time of this driver is about 15uS.

Driving High Voltage Laser Diodes

Some laser diodes have high forward voltage, such as 7V, while the laser driver ATLS4A201D has a maximum output voltage of 4V. This section tells a way to drive such laser diodes by using this laser driver.

The schematic is show as in Figure 8. Where Power Supply 1 is the power supply for the laser driver, Power Supply 2 is for increasing the laser driver's maximum output voltage.

Please notice that the power on sequence has to be in this way: turn on Power Supply 1, turn on Power Supply 2, then turn on the laser driver by driving SDN (Shutdown) pin to logic high.

The sequence for turning off the laser circuit is: turn off the SDN pin by pulling it down to the logic low; turn off Power Supply 1; and then, turn off power supply 2.

To make sure the circuit works ok: turn on the laser, measure LDA voltage, it should be between 1V to 3V, at room temperature, the ideal LDA voltage is around 2V.

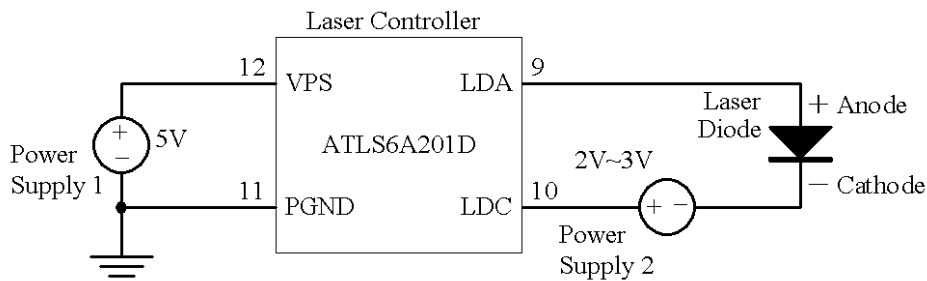


Figure 8. Driving High Voltage Laser Diodes

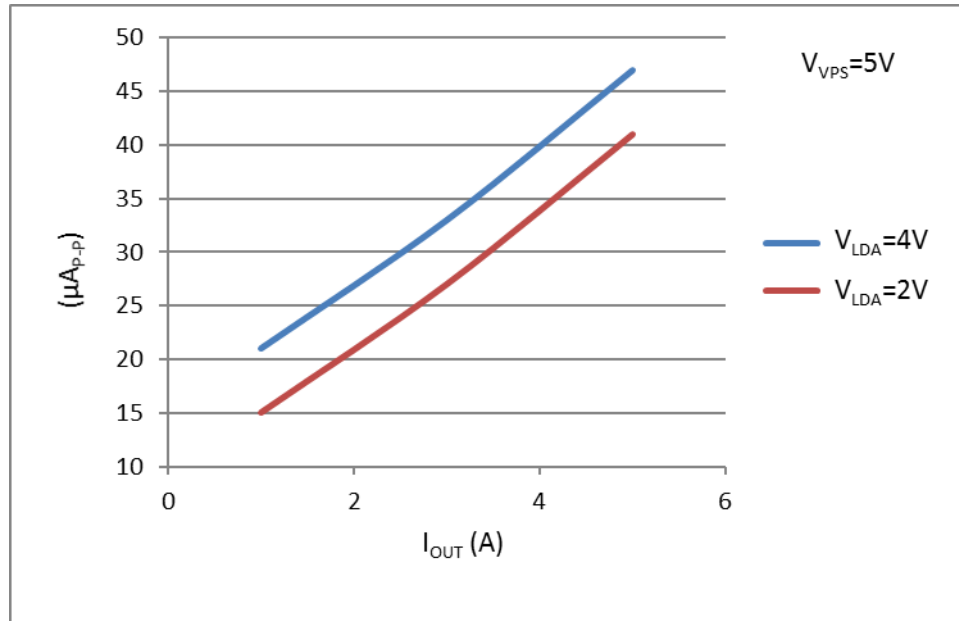


Figure 10. I_{OUT} vs. Output Current Noise@0.1Hz~10Hz

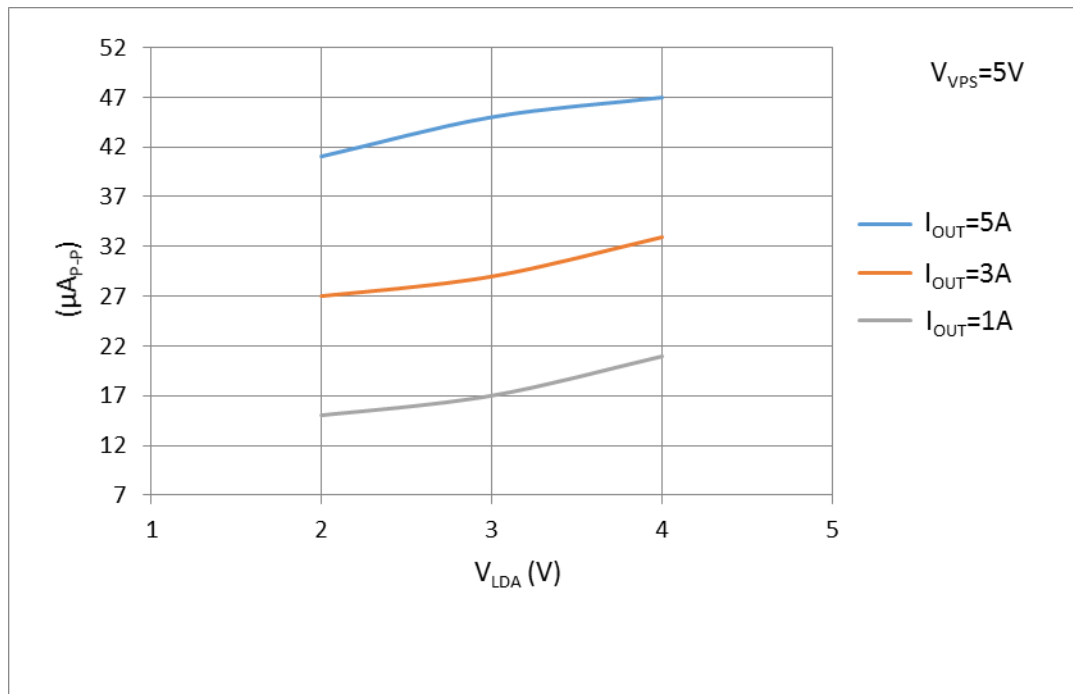


Figure 11. V_{LDA} vs. Output Current Noise@0.1Hz~10Hz



NOTE: The power supply may have overshoot, when happens, it may exceed the maximum allowed input voltage, 6V, of the controller and damage the controller permanently. To avoid this from happening, do the following:

1. Connect the controller solid well with the power supply before turning on the power.
2. Make sure that the power supply has sufficient output current. It is suggested that the power supply can supply 1.2 to 1.5 times the maximum current the controller requires.
3. When using a bench top power supply, set the current limit to >1.5 times higher than the maximum current the controller requires.

ORDERING INFORMATION

Table 3. Part Number

| Part Number | Description |
|---------------|--|
| ATLS6A201D | 6A constant current driver in DIP package |
| ATLS6A201D-PD | 6A constant current driver with a pull-down resistor of 55K to the ground in SDN pin |

Table 4. Unit Price

| Quantity (pcs) | 1 – 9 | 10 – 49 | 50 – 199 | 200 – 499 | ≥500 |
|----------------|--------|---------|----------|-----------|--------|
| ATLS6A201D | | | | | |
| ATLS6A201D-PD | \$88.2 | \$84.0 | \$79.8 | \$75.6 | \$71.4 |

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